

10005

1000 JAWABAN

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①

45 ①

$$z_1 = 40 + j30 \Omega = 50 \angle 36.87^\circ \Omega$$

$$z_2 = \cancel{0 + j(50 - 20)} + j(80 - 40)$$

$$z_2 = 0 + j40 = \cancel{40 + j} 40 \angle 90^\circ \Omega$$

$$z_3 = 0 + j(40 - 50) = 0 - j10 = 10 \angle -90^\circ \Omega$$

$$z_4 = 100 + j0 = 100 \angle 0^\circ$$

$$\bar{Y}_T = \bar{Y}_1 + \bar{Y}_2 + \bar{Y}_3 + \bar{Y}_4$$

$$= \frac{1}{z_1} + \frac{1}{z_2} + \frac{1}{z_3} + \frac{1}{z_4}$$

$$\bar{Y}_T = \frac{1}{50 \angle 36.87^\circ} + \frac{1}{40 \angle 90^\circ} + \frac{1}{10 \angle -90^\circ} + \frac{1}{100 \angle 0^\circ} \quad \Omega$$

$$\bar{Y}_T = 0.02 \angle -36.87^\circ + 0.025 \angle -90^\circ + 0.1 \angle 90^\circ + 0.01 \angle 0^\circ$$

$$\bar{Y}_T = 0.0154 - j0.0120 + 0 - j0.025 + 0 + j0.1 + 0.01 + j0$$

$$\bar{Y}_T = 0.0254 + j0.063 \quad \Omega = 0.0681 \angle 67.65^\circ$$

$$\text{Kor } \hat{Y}_T = G_T + jB_C = G_T + j\omega C$$

$$= G_T + j2\pi f C$$

$$\therefore B_C = 0.063 \quad \checkmark$$

$$\therefore 2\pi f C = 0.063$$

$$C = \frac{0.063}{2\pi f} \quad \text{F.}$$

on low $f = 60 \text{ Hz}$

$$C = \frac{0.063}{2\pi \times 60} = ~~0.00167~~ 1.671 \times 10^{-4} \text{ F.}$$

$$C = \frac{167.1}{~~0.0167~~} \mu\text{F} \quad \#$$

අග්‍රයේ ධාරාව $\hat{I}_{ag} = 216.5 \angle 12.83^\circ \text{ A}$

(3)

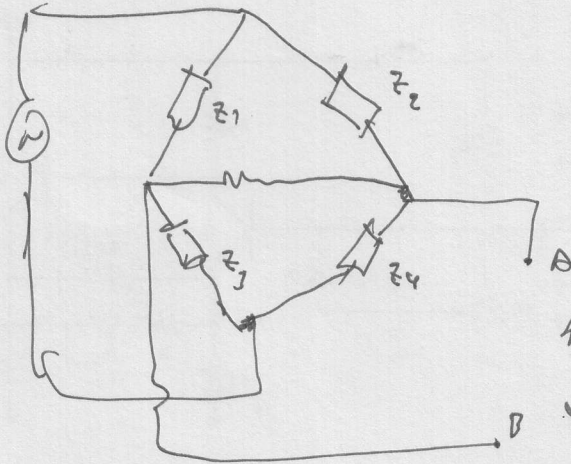
විචල්න (2)

සමතුලිත වස්තුව

$$\bar{X}_C = -j \frac{1}{2\pi f c}$$

$$= -j \frac{1}{\omega c}$$

$$\bar{X}_L = j\omega L = j2\pi f L$$



අග්‍රයේ $V_{AB} = 0 \text{ V}$

එහෙත් අග්‍රයේ $V_{AB} \neq 0 \text{ V}$.

විචල්න අග්‍රයේ $\frac{Z_1}{Z_3} = \frac{Z_2}{Z_4}$

එහෙත් $\frac{Z_1}{Z_2} = \frac{Z_3}{Z_4}$

එහෙත් $\frac{\bar{Z}_3}{\bar{Z}_1} = \frac{\bar{Z}_4}{\bar{Z}_2}$

එහෙත් $\bar{Z}_1 = 200 + j0 = 200 \angle 0^\circ$

$$\bar{Z}_2 = -j \frac{1}{\omega c} = -j \frac{1}{2\pi f c}$$

$$\omega = 2\pi f = 1000$$

$$f = \frac{1000}{2\pi} = 159.15 \text{ Hz}$$

$$\bar{z}_1 = -j \frac{1}{2 \times \pi \times 159.15 \times 1.25 \times 10^{-6}} \Omega$$

$$\bar{z}_2 = -j 800 \Omega = 0 - j 800 \Omega$$

$$\bar{z}_2 = 800 \angle -90^\circ \Omega$$

$$\bar{z}_3 = +j 2\pi f L = +j (2 \times \pi \times 159.15 \times 0.1)$$

$$\bar{z}_3 = j 99.99 = 0 + j 100 \Omega = 100 \angle +90^\circ$$

$$\bar{z}_4 = 400 + j 0 = 400 \angle 0^\circ \Omega$$

အိုပင် အသံကုန်

$$\frac{\bar{z}_1}{\bar{z}_2} = \frac{\bar{z}_3}{\bar{z}_4}$$

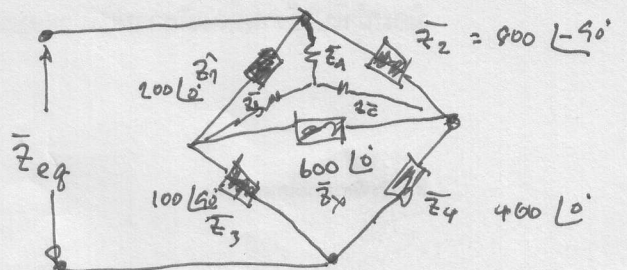
$$\frac{200 \angle 0^\circ}{800 \angle -90^\circ} = \frac{j 100}{400 \angle 0^\circ}$$

$$0.25 \angle 90^\circ = 0.25 \angle 90^\circ$$

အိုပင် အသံကုန်

မူလ \bar{z}_{eq} ကို ရှာရန်

အိုပင် အသံကုန် $\Delta \rightarrow Y$ ကို



$$\omega \quad \bar{z}_A = \frac{\bar{z}_1 \bar{z}_2}{\bar{z}_1 + \bar{z}_2 + \bar{z}_x}$$

$$\bar{z}_A = \frac{200 \angle 0^\circ \times 800 \angle -45^\circ}{200 \angle 0^\circ + 800 \angle -45^\circ + 600 \angle 0^\circ}$$

$$= \frac{160 \text{ k} \angle -45^\circ}{200 + j0 + 0 - j800 + 600 + j0}$$

$$= \frac{160 \text{ k} \angle -45^\circ}{800 - j800} = \frac{160 \text{ k} \angle -45^\circ}{1,131.37 \angle -45^\circ} \quad \Omega$$

$$\bar{z}_A = 141.42 \angle -45^\circ \quad \Omega$$

$$\bar{z}_b = \frac{\bar{z}_1 \times \bar{z}_x}{\bar{z}_1 + \bar{z}_2 + \bar{z}_x} = \frac{200 \angle 0^\circ \times 600 \angle 0^\circ}{1131.37 \angle -45^\circ}$$

$$\bar{z}_b = \frac{120 \text{ k} \angle 0^\circ}{1131.37 \angle -45^\circ} = 106.06 \angle 45^\circ \quad \Omega$$

$$\bar{z}_c = \frac{\bar{z}_2 \times \bar{z}_x}{\bar{z}_1 + \bar{z}_2 + \bar{z}_x} = \frac{800 \angle -45^\circ \times 600 \angle 0^\circ}{1131.37 \angle -45^\circ}$$

$$\bar{z}_c = \frac{480 \text{ k} \angle -45^\circ}{1131.37 \angle -45^\circ} = 424.26 \angle -45^\circ \quad \Omega$$

$$\bar{z}_{T1} = \bar{z}_2 + \bar{z}_3 = 106.06 \angle 45^\circ + 100 \angle 90^\circ$$

$$\begin{aligned} \bar{z}_{T1} &= 74.99 + j74.99 + 0 + j100 \\ &= 74.99 + j174.99 \end{aligned}$$

$$\bar{z}_{T1} = 190.38 \angle 66.80^\circ \quad \Omega$$

$$\bar{z}_{T2} = \bar{z}_4 + \bar{z}_5 = 424.26 \angle -45^\circ + 400 \angle 0^\circ$$

$$\bar{z}_{T2} = 299.99 - j299.99 + 400 + j0$$

~~$$\bar{z}_{T2} = 300 - j300$$~~

$$\bar{z}_{T2} = 700 - j300 \quad \Omega$$

$$\bar{z}_{T2} = 761.57 \angle -23.15^\circ$$

$$\bar{z}_{T3} = \bar{z}_{T1} \parallel \bar{z}_{T2} = \frac{\bar{z}_{T1} \times \bar{z}_{T2}}{\bar{z}_{T1} + \bar{z}_{T2}}$$

~~$$\bar{z}_{T3} = \frac{190.38 \angle 66.80^\circ \times 761.57 \angle -23.15^\circ}{190.38 \angle 66.80^\circ + 761.57 \angle -23.15^\circ}$$~~

$$\bar{z}_{T3} = \frac{144.98 \angle 43.61^\circ}{74.99 + j174.99 + 700 - j300} \quad \Omega$$

$$\bar{z}_{T3} = \frac{144.98 \angle 43.61^\circ}{774.99 - j125.01} = \frac{144.98 \angle 43.61^\circ}{788.00 \angle -9.163^\circ}$$

$$\bar{z}_{T3} = 0.1846 \angle 52.773^\circ \Omega$$

$$\bar{z}_{eq} = \bar{z}_A + \bar{z}_{T3} = 141.42 \angle -45^\circ + 0.1846 \angle 52.773^\circ$$

$$\bar{z}_{eq} = +100 - j100 + 0.1116 + j0.1469$$

$$\bar{z}_{eq} = 100.1116 - j99.88 \Omega$$

$$\bar{z}_{eq} = 141.41 \angle -44.93^\circ \Omega$$

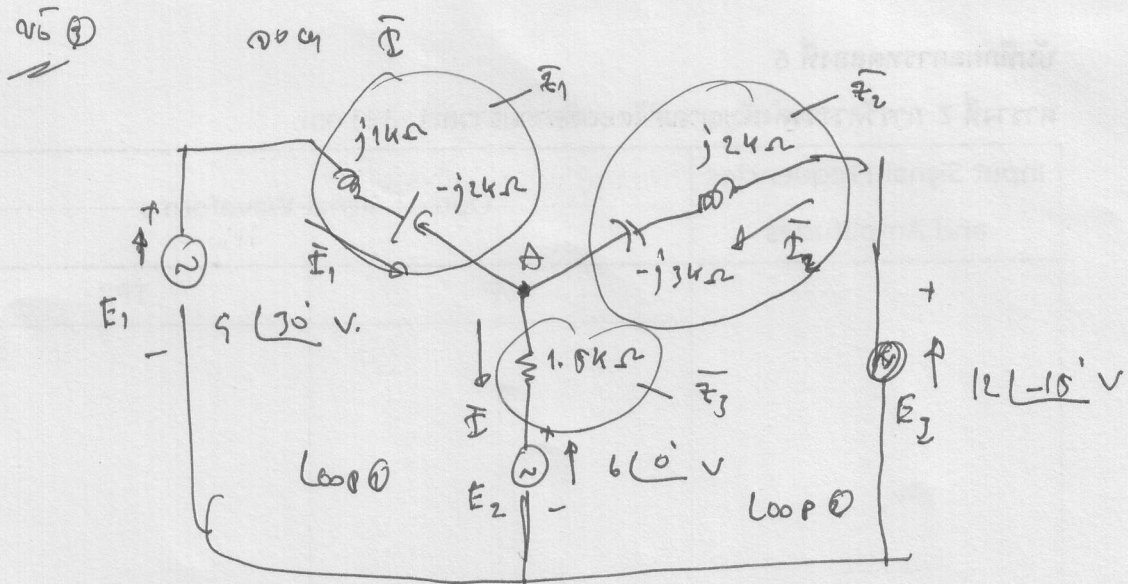
$$\bar{z}_{eq} = 216.4 \angle 12.53^\circ = (\bar{z}_1 + \bar{z}_3) \parallel (\bar{z}_2 + \bar{z}_4)$$

8.2.10 100 (0)

15.01.2020

$$\bar{I} = 8.82 \angle 8.94^\circ \text{ mA}$$

⑧



Use superposition theorem $\bar{I} \rightarrow k\Omega \rightarrow I \rightarrow \text{mA}$.

Node A

$$\bar{I}_1 + \bar{I}_2 = \bar{I} \quad \text{--- (1)}$$

$$\bar{Z}_1 = 0 + j(1 - 2) = 0 - j = 1 \angle -90^\circ \text{ k}\Omega$$

$$\bar{Z}_2 = 0 + j(2 - 3) = 0 - j = 1 \angle -90^\circ \text{ k}\Omega$$

$$\bar{Z}_3 = 1.5 \angle 0^\circ \text{ k}\Omega = 1.5 + j0 \text{ k}\Omega$$

Loop 1

$$-9 \angle 30^\circ + \bar{I}_1 \bar{Z}_1 + \bar{I} \bar{Z}_3 + 6 \angle 0^\circ = 0$$

$$\text{or } \bar{I} = \bar{I}_1 + \bar{I}_2$$

$$-9 \angle 30^\circ + \bar{I}_1 \bar{Z}_1 + (\bar{I}_1 + \bar{I}_2) \bar{Z}_3 + 6 \angle 0^\circ = 0$$

$$(\bar{Z}_1 + \bar{Z}_3) \bar{I}_1 + \bar{Z}_3 \bar{I}_2 = 9 \angle 30^\circ - 6 \angle 0^\circ$$

$$(0 - j + 1.5 + j0) \bar{I}_1 + (1.5 + j0) \bar{I}_2 = 7.944 + j4.5 - (6 + j0)$$

$$(1.5 - j) \bar{I}_1 + (1.5 + j0) \bar{I}_2 = 1.794 + j4.5$$

$$1.802 \angle -33.69^\circ \bar{I}_1 + 1.5 \angle 0^\circ \bar{I}_2 = 4.844 \angle 68.26^\circ \quad \text{--- (1)}$$

Loop (2)

$$-6 \angle 0^\circ - \bar{Z}_3 \bar{I} - \bar{Z}_2 \bar{I}_2 + 12 \angle -15^\circ = 0$$

$$-\bar{Z}_3 (\bar{I}_1 + \bar{I}_2) - \bar{Z}_2 \bar{I}_2 = -12 \angle -15^\circ + 6 \angle 0^\circ$$

$$-\bar{Z}_3 \bar{I}_1 + (-\bar{Z}_3 - \bar{Z}_2) \bar{I}_2 = -12 \angle -15^\circ + 6 \angle 0^\circ$$

$$-\bar{Z}_3 \bar{I}_1 - (\bar{Z}_3 + \bar{Z}_2) \bar{I}_2 = -12 \angle -15^\circ + 6 \angle 0^\circ$$

$$-(1.5 + j0) \bar{I}_1 - (1.5 + j0 + 0 - j) \bar{I}_2 =$$

$$(-1.5 - j0) \bar{I}_1 - (1.5 - j) \bar{I}_2 = -(11.59 - j3.1) + 6 + j0$$

$$= -11.59 + j3.1 + 6 + j0$$

$$= -5.59 + j3.1$$

$$1.5 \angle 180^\circ \bar{I}_1 + (-1.5 + j) \bar{I}_2 = -5.59 + j3.1$$

$$1.5 \angle 180^\circ \bar{I}_1 + 1.802 \angle 146.7^\circ \bar{I}_2 = 6.39 \angle 151^\circ \quad \text{--- (2)}$$

$$\Delta = \begin{vmatrix} 1.802 \angle -77.69^\circ & 1.5 \angle 0^\circ \\ 1.5 \angle 180^\circ & 1.802 \angle 146.3^\circ \end{vmatrix} = (3.247 \angle 112.61^\circ) - (2.25 \angle 180^\circ)$$

$$\Delta = -1.248 + j 2.997 - (-2.25 + j 0)$$

$$\Delta = -1.248 + j 2.997 + 2.25 - j 0$$

$$\Delta = 1.005 + j 2.997 = 3.16 \angle 71.46^\circ$$

$$\bar{E}_1 = \begin{vmatrix} 4.844 \angle 68.26^\circ & 1.5 \angle 0^\circ \\ 6.39 \angle 151^\circ & 1.802 \angle 146.3^\circ \end{vmatrix}$$

Δ

$$= \frac{8.728 \angle 214.56^\circ - \cancel{2.525} \angle 58.5^\circ}{3.16 \angle 71.46^\circ}$$

$$= \frac{-7.187 - j 4.95 - (-8.38 + j 4.646)}{1.004 + j 2.997}$$

$$= \frac{-7.187 - j 4.95 + 8.38 - j 4.646}{3.16 \angle 71.46^\circ}$$

$$\vec{\Phi}_1 = \frac{1.193 - j 9.596}{3.16 \angle 71.46^\circ} = \frac{9.66 \angle -82.91^\circ}{3.16 \angle 71.46^\circ}$$

$$\vec{\Phi}_1 = 3.056 \angle -154.87^\circ \quad A$$

$$\vec{\Phi}_2 = \begin{vmatrix} 1.802 \angle -33.65^\circ & 4.844 \angle 65.26^\circ \\ 1.5 \angle 186^\circ & 6.39 \angle 151^\circ \end{vmatrix}$$

$$3.16 \angle 72.46^\circ$$

$$\vec{\Phi}_2 = \frac{11.514 \angle 117.31^\circ - (7.266 \angle 248.26^\circ)}{3.16 \angle 72.46^\circ}$$

$$= \frac{-5.28 + j 10.23 - (-2.65 - j 6.949)}{3.16 \angle 72.46^\circ}$$

$$= \frac{-5.28 + j 10.23 + 2.65 + j 6.949}{3.16 \angle 72.46^\circ}$$

$$= \frac{-2.63 + j 16.979}{3.16 \angle 72.46^\circ} = \frac{19.175 \angle 98.67^\circ}{3.16 \angle 72.46^\circ}$$

$$\vec{\Phi}_2 = 5.435 \angle 29.21^\circ$$

(12)

$$\bar{I}_2 = \bar{I}_1 + \bar{I}_2 = 3.056 \angle -154.89^\circ + 5.438 \angle 27.21^\circ$$

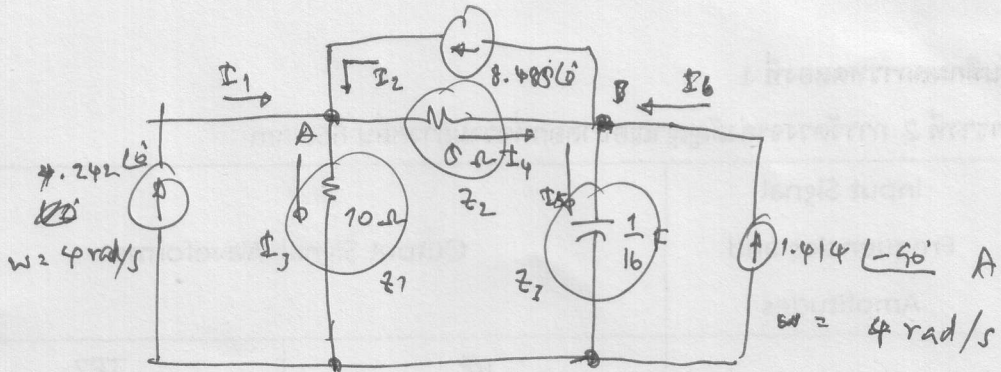
$$\bar{I}_2 = -2.966 - j1.249 + 4.833 + j2.485$$

$$\bar{I}_2 = 2.067 + j1.188$$

$$\bar{I}_2 = 2.384 \angle 29.88^\circ \text{ mA} \longrightarrow \text{⊗}$$

$$V_B = 15 \angle -130^\circ \text{ V}$$

$\omega = 4$



$$Z_1 = 10 \Omega = 10 \angle 0^\circ \Omega$$

$$Z_2 = 5 \Omega = 5 \angle 0^\circ \Omega$$

$$Z_3 = -j \frac{1}{\omega C} = -j \frac{1}{2\pi f C}$$

$$\omega = 4 \text{ rad/s} = 2\pi f$$

$$f = \frac{4}{2\pi} = 0.6366 \text{ Hz}$$

$$Z_3 = -j \frac{1}{2\pi \times 0.6366 \times \frac{1}{16}} = -j 4 \Omega$$

$$Z_3 = 4 \angle -90^\circ \Omega$$

Node A

$$I_1 + I_2 = I_3 + I_4$$

$$4.242 \angle 0^\circ + 8.485 \angle 0^\circ = \frac{V_A}{Z_1} + \frac{V_A - V_B}{Z_2}$$

$$4.242 + j0 + 8.485 + j0 = \frac{V_A}{10 \angle 0^\circ} + \frac{V_A}{5 \angle 0^\circ} - \frac{V_B}{5 \angle 0^\circ}$$

$$12.729 \angle 0^\circ + j0 = \left(\frac{1}{10 \angle 0^\circ} + \frac{1}{5 \angle 0^\circ} \right) V_A - \frac{1}{5 \angle 0^\circ} V_B$$

$$\dots = [(0.1 + 0.2) + j0] V_A - 0.2 \angle 0^\circ V_B$$

$$12.729 \angle 0^\circ = 0.3 \angle 0^\circ V_A - 0.2 \angle 0^\circ V_B \quad \text{--- (1)}$$

$$0.2 \angle 0^\circ V_B = 0.3 \angle 0^\circ V_A - 12.729 \angle 0^\circ$$

$$V_B = \frac{0.3 \angle 0^\circ}{0.2 \angle 0^\circ} V_A - \frac{12.729 \angle 0^\circ}{0.2 \angle 0^\circ}$$

$$V_B = 1.5 \angle 0^\circ V_A - 63.635 \angle 0^\circ \quad \text{--- (2)}$$

Node B
→

$$I_4 + I_6 = I_2 + I_5$$

$$I_6 - I_2 = I_5 - I_4$$

$$1.414 \angle -45^\circ - (8.485 \angle 0^\circ) = \frac{V_B}{Z_3} - \frac{(V_A - V_B)}{Z_2}$$

$$0 - j1.414 - (8.485 + j0) = \frac{V_B}{4 \angle -45^\circ} - \frac{(V_A - V_B)}{5 \angle 0^\circ}$$

$$0 - j1.414 - 8.485 - j0 = \frac{V_B}{4 \angle -45^\circ} - \frac{V_A}{5 \angle 0^\circ} + \frac{V_B}{5 \angle 0^\circ}$$

$$-8.485 - j1.414 = 0.25 \angle 45^\circ V_B - 0.2 \angle 0^\circ V_A + 0.2 \angle 0^\circ V_B$$

$$8.602 \angle -170.57^\circ = (0.25 \angle 45^\circ + 0.2 \angle 0^\circ) V_B - 0.2 \angle 0^\circ V_A$$

$$0.2 \angle 0^\circ V_A = [0 + j0.25 + 0.2 + j0] V_B - (8.602 \angle 170.5^\circ)$$

$$0.2 \angle 0^\circ V_A = [0.2 + j0.25] V_B - (-8.485 - j1.414)$$

$$0.2 \angle 0^\circ V_A = (0.2 + j0.25) V_B + (8.485 + j1.414)$$

$$0.2 \angle 0^\circ V_A = 0.320 \angle 51.34^\circ V_B + 8.602 \angle 9.461^\circ$$

$$V_A = \frac{0.320 \angle 51.34^\circ}{0.2 \angle 0^\circ} V_B + \frac{8.602 \angle 9.461^\circ}{0.2 \angle 0^\circ}$$

$$V_A = 1.6 \angle 51.34^\circ V_B + 43.01 \angle 9.461^\circ \quad \text{--- (1)}$$

من (1) نستخرج (2)

$$V_B = 1.5 \angle 0^\circ [1.6 \angle 51.34^\circ V_B + 43.01 \angle 9.461^\circ] - 63.635 \angle 0^\circ$$

$$V_B = 2.4 \angle 51.34^\circ V_B + 64.515 \angle 9.461^\circ - 63.635 \angle 0^\circ$$

$$(1 - 2.4 \angle 51.34^\circ) V_B = 64.515 \angle 9.461^\circ - 63.635 \angle 0^\circ$$

$$[1 + j0 - (2.499 + j1.894)] V_B = 63.637 + j10.6 - (63.635 + j0)$$

$$[1 - j^0 = 1.499 - j1.894] V_B = \cancel{63.637} + j10.6 - \cancel{63.635} - j^0$$

$$(-0.499 - j1.894) V_B = j10.6$$

~~$$1.939 \angle -104.51^\circ V_B = 10.6 \angle 90^\circ$$~~

$$V_B = \frac{10.6 \angle 90^\circ}{1.939 \angle -104.51^\circ}$$

$$V_B = 5.46 \angle 154.51^\circ \quad V.$$

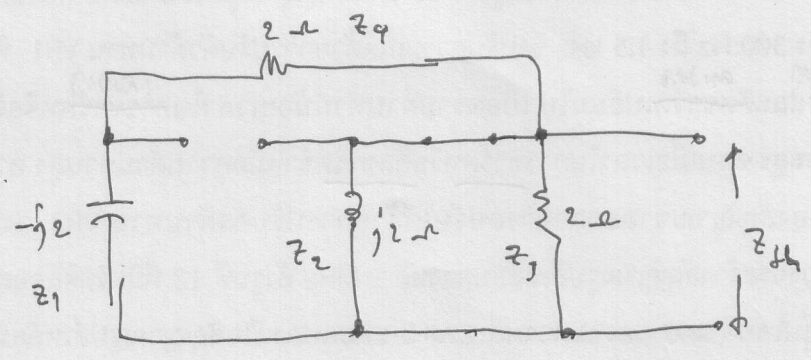
V. ~~_____~~

$V_o = 5.66 \angle -45^\circ \text{ V}$

0.5

in Z_H

Now Load $P_{2\Omega}$ in Z_H



$Z_H = (Z_2 \parallel Z_3) \parallel (Z_1 + Z_4)$

$Z_1 = 0 - j2 = 2 \angle -90^\circ \Omega$

$Z_2 = 0 + j2 = 2 \angle 90^\circ \Omega$

$Z_3 = 2 \Omega = 2 + j0 = 2 \angle 0^\circ \Omega$

$Z_4 = 2 + j0 = 2 \angle 0^\circ \Omega$

$Z_2 \parallel Z_3 = \frac{2 \angle 90^\circ \times 2 \angle 0^\circ}{2 \angle 90^\circ + 2 \angle 0^\circ} = \frac{4 \angle 90^\circ}{0 + j2 + 2 + j0} = \frac{4 \angle 90^\circ}{2 + j2} = \frac{4 \angle 90^\circ}{2.828 \angle 45^\circ}$

$Z_2 \parallel Z_3 = 1.414 \angle 45^\circ \Omega$

$Z_1 + Z_4 = 0 - j2 + (2 + j0) = 2 - j2 = 2.828 \angle -45^\circ$

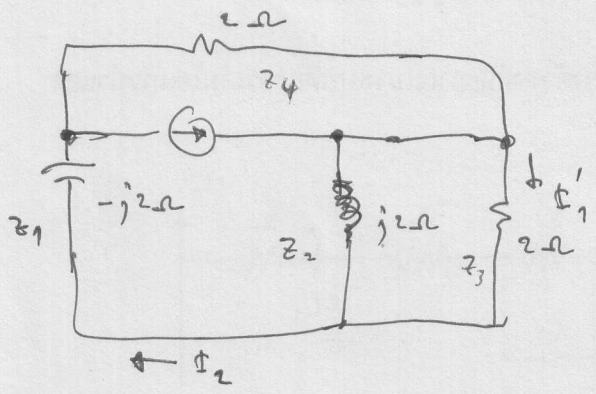
$Z_H = \frac{1.414 \angle 45^\circ \times 2.828 \angle -45^\circ}{1.414 \angle 45^\circ + 2.828 \angle -45^\circ}$

$$Z_{th} = \frac{3.998 \angle 0^\circ}{0.999 + j0.999 + 1.999 - j1.999}$$

$$Z_{th} = \frac{3.998 \angle 0^\circ}{2.998 - j} = \frac{3.998 \angle 0^\circ}{3.16 \angle -18.44^\circ}$$

$$Z_{th} = 1.265 \angle 18.44^\circ \Omega$$

Find the current in the load (upper position) in Φ_1



$$Z_{T1} = Z_2 \parallel Z_3 = 1.414 \angle 45^\circ$$

$$Z_{T2} = Z_{T1} + Z_1 = 1.414 \angle 45^\circ + 0 - j2 = 0.999 + j0.999 + 0 - j2$$

$$Z_{T2} = 0.999 - j1.01 \Omega = 1.414 \angle -45^\circ$$

$$I_2 = \frac{4 \angle 0^\circ \times 2 \angle 0^\circ}{2 \angle 0^\circ + 1.414 \angle -45^\circ} = \frac{8 \angle 0^\circ}{2 + j0 + 0.999 - j1}$$

$$\Phi_2 = \frac{8 \angle 0^\circ}{2.999 - j1} = \frac{8 \angle 0^\circ}{3.152 \angle -18.44^\circ} = 2.538 \angle 18.44^\circ A$$

$$\bar{\Phi}_T = \frac{12 \angle 0^\circ}{2 \angle -53.1^\circ} = 6 \angle +53.1^\circ \text{ A}$$

$$\Phi_1'' = \frac{\Phi_T \times \frac{2}{2-j2}}{2 \angle 0^\circ + 2.828 \angle -45^\circ} = \frac{6 \angle 53.1^\circ \times 2.828 \angle -45^\circ}{2 \angle 0^\circ + 2.828 \angle -45^\circ}$$

$$\Phi_1'' = \frac{16.968 \angle 8.1^\circ}{2+j0 + 2-j2} = \frac{16.968 \angle 8.1^\circ}{4-j2} = \frac{16.968 \angle 8.1^\circ}{4.472 \angle -26.56^\circ}$$

$$\Phi_1'' = 3.794 \angle 34.66^\circ \text{ A}$$

$$\Phi_{2R} = \Phi_1' + \Phi_1'' = 1.768 \angle 63.45^\circ + 3.794 \angle 34.66^\circ$$

$$\Phi_{2R} = 0.989 + j 1.874 + 3.12 + j 2.157$$

$$\Phi_{2R} = 3.909 + j 3.735 = 5.40 \angle 43.7^\circ$$

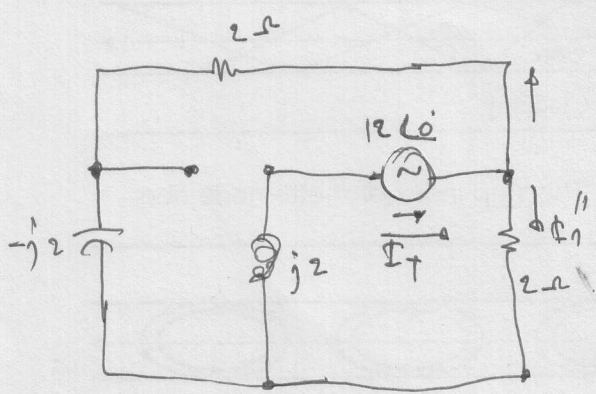
$$\bar{V}_0 = \Phi_{2R} \times 2R = 5.40 \angle 43.7^\circ \times 2 \angle 0^\circ$$

$$\bar{V}_0 = 10.8 \angle 43.7^\circ \text{ V}$$

$$\Phi_1' = \frac{\Phi_2 \times j2}{0 + j2 + 2 + j0} = \frac{2.538 \angle 18.45^\circ \times 2 \angle 90^\circ}{2 + j2}$$

$$\Phi_1' = \frac{5 \angle 108.45^\circ}{2.828 \angle 45^\circ} = 1.768 \angle 63.45^\circ \text{ A}$$

Req // Φ_1''



$$\bar{z}_{T3} = 2 + j0 + 0 - j2 = 2 - j2 = 2.828 \angle -45^\circ \Omega$$

$$\bar{z}_{T4} = 2 \angle 0^\circ // \bar{z}_{T3} = \frac{2 \angle 0^\circ \times 2.828 \angle -45^\circ}{2 \angle 0^\circ + 2.828 \angle -45^\circ}$$

$$\bar{z}_{T4} = \frac{5.656 \angle -45^\circ}{2 + j0 + 1.99 - j1.99} = \frac{5.656 \angle -45^\circ}{3.99 - j1.99}$$

$$\bar{z}_{T4} = \frac{5.656 \angle -45^\circ}{4.458 \angle -26.5^\circ} = 1.268 \angle -18.5^\circ \Omega$$

$$\bar{z}_T = 0 + j2 + \bar{z}_{T4} = 0 + j2 + 1.20 - j0.40$$

$$\bar{z}_T = 1.20 - j1.6 = 2 \angle -53.1^\circ \Omega$$

$$\bar{\Phi}_T = \frac{12 \angle 0^\circ}{2 \angle -53.1^\circ} = 6 \angle +53.1^\circ \text{ A}$$

$$\Phi_1'' = \frac{\Phi_T \times \cancel{2} (2-j2)}{2 \angle 0^\circ + 2.828 \angle -45^\circ} = \frac{6 \angle 53.1^\circ \times 2.828 \angle -45^\circ}{2 \angle 0^\circ + 2.828 \angle -45^\circ}$$

$$\Phi_1'' = \frac{16.968 \angle 8.1^\circ}{2+j0 + 2-j2} = \frac{16.968 \angle 8.1^\circ}{4-j2} = \frac{16.968 \angle 8.1^\circ}{4.472 \angle -26.56^\circ}$$

$$\Phi_1'' = 3.794 \angle 34.66^\circ \text{ A}$$

$$\Phi_{2R} = \Phi_1' + \Phi_1'' = 1.968 \angle 63.45^\circ + 3.794 \angle 34.66^\circ$$

$$\Phi_{2R} = 0.989 + j 1.874 + 3.12 + j 2.157$$

$$\Phi_{2R} = 3.909 + j 3.735 = 5.40 \angle 43.7^\circ$$

$$\bar{V}_0 = \Phi_{2R} \times 2R = 5.40 \angle 43.7^\circ \times 2 \angle 0^\circ$$

$$\bar{V}_0 = 10.8 \angle 43.7^\circ \text{ V}$$

$$\vec{I}_{zA} = \frac{\vec{E}_{AB}}{\vec{Z}_A} = \frac{4.775W \angle 30^\circ}{63.24 \angle 18.43^\circ} = 75 \angle 11.57^\circ \text{ A} \quad \text{--- (4)}$$

$$\vec{I}_{zB} = \frac{\vec{E}_{BC}}{\vec{Z}_B} = \frac{4.775W \angle -90^\circ}{63.24 \angle 18.43^\circ} = \cancel{75} 75 \angle -108.43^\circ \text{ A} \quad \text{--- (5)}$$

$$\vec{I}_{zC} = \frac{\vec{E}_{CA}}{\vec{Z}_C} = \frac{4.775W \angle 150^\circ}{63.24 \angle 18.43^\circ} = 75 \angle 131.55^\circ \text{ A} \quad \text{--- (6)}$$

نصلي 2 في دوائر 1 و 2: 27V.

$$\begin{aligned} \vec{I}_{AL} &= \vec{I}_{zA} - \vec{I}_{zC} \\ &= 75 \angle 11.57^\circ - 75 \angle 131.55^\circ \text{ A} \\ &= 73.47 + j15.042 - (-45.94 + j56.128) \\ &= 73.47 + j15.042 + 45.94 - j56.128 \\ &= 123.21 - j41.086 \text{ A} \\ &= 129.87 \angle -18.46^\circ \text{ A} \end{aligned}$$

$$\begin{aligned} \vec{I}_{BL} &= \vec{I}_{zB} - \vec{I}_{zA} \\ &= 75 \angle -108.43^\circ - 75 \angle 11.57^\circ \\ &= -23.91 - j71.15 - (73.47 + j15.042) \\ &= -23.91 - j71.15 - 73.47 - j15.042 \\ &= \end{aligned}$$

$$\bar{I}_{BL} = -49.18 - j86.142 \text{ A}$$

$$\bar{I}_{BL} = 129.896 \angle -138.42^\circ \text{ A}$$

$$\bar{I}_{CL} = \bar{I}_{BC} - \bar{I}_{2B}$$

$$I = ~~95~~ 95 \angle 131.55^\circ - 95 \angle -108.43^\circ \text{ A}$$

$$I = -49.74 + j56.128 - (-23.71 - j71.15)$$

$$I = -49.74 + j56.128 + 23.71 + j71.15$$

$$I = -26.03 + j127.27 \text{ A}$$

$$\bar{I}_{CL} = 129.50 \angle 101.55^\circ \text{ A}$$

η = 0.95, load 3 phase pu Δ change

$$\bar{S}_T = 3 V_p \bar{I}_p$$

$$\bar{S}_T = 3 \times 4.775 \text{ kV} \angle -30^\circ \times 95 \angle 11.57^\circ \text{ A}$$

$$S_T = 1.0743 \angle -18.43^\circ \text{ MVA}$$

$$\bar{S}_T = \bar{P}_T + j \bar{Q}_T$$

$$\bar{S}_T = 1.019 - j0.339 \text{ MVA}$$

$$P_T = 1019 \text{ kW}$$

ကန့်သတ်ပါဝင်မှု $\bar{S}_T = 1074 \text{ kVA}$

ကန့်သတ်ပါဝင်မှု $\bar{P}_T = 1.019 \text{ MWatt} = 1019 \text{ kWatt}$

ကန့်သတ်ပါဝင်မှု $\bar{Q}_T = 339 \text{ kVar}$

$\cos \theta = \text{p.f.} = \frac{\bar{P}_T}{\bar{S}_T} = \frac{1019}{1074} = 0.948$

0.948

$\theta = \cos^{-1} 0.948$

$\theta = 18.55^\circ$
